Probabilistic Verification of Multiple-Valued Functions

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Abstract

This paper describes a probabilistic method for verifying the equivalence of two multiple-valued functions. Each function is hashed to an integer code by transforming it to a integer-valued polynomial and the equivalence of two polynomials is checked probabilistically. The hash codes for two equivalent functions are always the same. Thus, the equivalence of two functions can be verified with a known probability of error, arising from collisions between inequivalent functions. Such a probabilistic verification can be an attractive alternative for verifying functions that are too large to be handled by deterministic verification methods.

1 Introduction

In recent years, advances in integrated circuit technology made feasible fabrication of several commercial products benefiting from multiple-valued logic, such as 256-Mbit 4-valued flash memory [1] and 4-Gbit 4-valued DRAM [2]. These products can be seen as first steps toward recognition of the increasing role of multiple-valued logic in the next generation of electronic systems. However, for further practical utilization, efficient computer-aided tools for design, testing and verification of multiple-valued logic circuits are needed. Some existing tools, such as Berkeley’s tool for verification and synthesis VIS [3], provide a solution for the special case of multiple-valued input binary-valued output functions, but the general problem is still open.

This paper focuses on the problem of verification of multiple-valued functions. Up to now, very little research is done in this area. Some techniques for verification of Boolean circuits, such as random simulation or symbolic simulation, can be directly applied to verification of multiple-valued logic case [4], [5]. Similarly, verification procedures employing Reduced Ordered Binary Decision Diagrams (ROBDDs) [6] can adapted to Multiple-valued Decision Diagrams (MDD) [7]. However, the MDD verification methods representing functions as single, monolithic graph might be infeasible for large functions. We believe that deterministic methods of verification will not be practical for the multiple-valued logic domain due to the increasing complexity of the problem.
In this paper we present a probabilistic method for design verification of multiple-valued logic functions, which generalizes the method introduced in [8]. We define a functional transformation $A$ which converts a multiple-valued function $f : M^p \rightarrow M$ on a set $M \triangleq \{0, 1, \ldots, m-1\}$ into a polynomial of type $A_m[f] : Z_p \rightarrow Z_p$ over a finite field of integers $Z_p$ modulo $p$, for some prime $p$. This polynomial is used to generate a hash code for $f$, by evaluating the value of $A_m[f](x_1, \ldots, x_n)$ for randomly chosen values of $x_i$ from $Z_p$, $i \in \{1, \ldots, n\}$. The hash codes for two equivalent functions are always the same. Thus, the equivalence of two functions can be verified with a known probability of error, arising from collisions between inequivalent functions.

The paper is organized as follows. In Section 1, the $A$-transform is defined and its properties are studied. Section 2 shows how to compute the integer-valued polynomial given by $A$-transform. Section 3 defines the notion of hash code for a function. In Section 4, we give a conclusion and describe the topics for further research.

2 Definition and properties of the $A$-transform

To define the transformation $A$, we associate a key polynomial with each of the $m^n$ input assignments of a multiple-valued function $f(x_1, \ldots, x_n)$. We then sum all the key polynomials of assignments producing the non-zero output value of $f$, and interpret the result as an integer-valued function $A_m[f](x_1, \ldots, x_n)$ over $Z_p$.

The key polynomial for a given row of the truth table is a product of terms, where each term is associated with a particular input variable $x_i$, $i \in \{1, \ldots, n\}$. If $b_i$ represents the value of $x_i$ in a given row of the truth table, then the corresponding term $w(b_i, x_i)$ in the key polynomial is defined as follows:

**Definition 1** For any $m > 1$, $w : Z_p \times Z_p \rightarrow Z_p$ is defined by

$$w(b, x) = \sum_{i=0}^{m-1} \left( \prod_{j \in M \setminus \{i\}} \frac{j - b}{j - i} \cdot \prod_{j \in M \setminus \{i\}} \frac{j - x}{j - i} \right)$$

It is easy to see that

$$\prod_{j \in M \setminus \{i\}} \frac{j - b}{j - i} = 1 \text{ for } b = i \text{ and } \prod_{j \in M \setminus \{i\}} \frac{j - b}{j - i} = 0 \text{ for } b \neq i.$$ Therefore, parameter $b$ acts as a selector between the terms $\prod_{j \in M \setminus \{i\}} \frac{j - x}{j - i}$ for different values of $i \in M$, i.e. $w(0, x) = \prod_{j \in M \setminus \{0\}} \frac{j - x}{j}$, $w(1, x) = \prod_{j \in M \setminus \{1\}} \frac{j - x}{j - 1}$, and so on. On the other hand, each of the terms $\prod_{j \in M \setminus \{i\}} \frac{j - x}{j}$, represents a polynomial which evaluates to 1 for $x = i$ and evaluates to 0 for $x \in M \setminus \{i\}$.

So, such a polynomial has a behavior similar to the behavior of the literal operator $\hat{x}$:

$$\hat{x} \triangleq \begin{cases} m - 1 & \text{if } x = i \\ 0 & \text{otherwise} \end{cases}$$

except that for $x = i$ the literal $\hat{x}$ evaluates to $m - 1$, and not to 1.
The **key polynomial** $W_n$ for an assignment $(b_1, \ldots, b_n) \in M^n$ of $n$ variables is defined as the product of the $w(b_i, x_i)$ terms, $i \in \{1, \ldots, n\}$:

**Definition 2** For any $n \geq 0$ and $m > 1$, the **key polynomial** $W_n : Z_p^{2n} \rightarrow Z_p$ is defined by

$$W_n(b_1, \ldots, b_n, x_1, \ldots, x_n) = \prod_{i=1}^{n} w(b_i, x_i)$$

For example, for $m = 3$, $W_2(0, 1, x_1, x_2) = \frac{1}{2}(1 - x_1)(2 - x_1)x_2(2 - x_2)$. Similarly, $W_2(1, 2, x_1, x_2) = x_1(2 - x_1)(-\frac{1}{2}x_2)(1 - x_2)$.

Now, we define the transformation $A$ as a sum of key polynomials $W_n$ for all assignments $(b_1, \ldots, b_n) \in M^n$, each multiplied by the value of $f$ for the corresponding assignment. We give a definition, applicable for general functions $Z_p^n \rightarrow Z_p$ over the field $Z_p$. Note that, since $M \subset Z_p$, the multiple-valued functions $M^n \rightarrow M$ are a subset of the field functions $Z_p^n \rightarrow Z_p$. While a field function is defined for inputs $x_i \notin M$ as well, the values which the function produces for such assignments do not participate in the definition. To distinguish between multiple-valued and field functions, throughout the paper we use the unsubscribed letters $f, g$ for multiple-valued functions of type $M^n \rightarrow M$ and the subscripted letters $f_z, g_z$ for field functions of type $Z_p^n \rightarrow Z_p$.

**Definition 3** Given a function of type $f_z : Z_p^n \rightarrow Z_p$ and $m > 1$, the polynomial $A_m[f_z] : Z_p^n \rightarrow Z_p$ is defined by

$$A_m[f_z](x_1, \ldots, x_n) = \sum_{(b_1, \ldots, b_n) \in M^n} f_z(b_1, \ldots, b_n) \cdot W_n(b_1, \ldots, b_n, x_1, \ldots, x_n)$$

For example, for $m = 3$ and $n = 2$, the polynomial $A_3[f_z](x_1, x_2)$ is given by

$$A_3[f_z](x_1, x_2) = f(0, 0) \cdot \frac{1}{2}(1 - x_1)(2 - x_1)(1 - x_2)(2 - x_2) +$$
$$+ f(0, 1) \cdot \frac{1}{2}(1 - x_1)(1 - x_2)(2 - x_2) +$$
$$+ f(0, 2) \cdot \frac{1}{2}(1 - x_1)(2 - x_1)(1 - x_2) +$$
$$+ f(1, 0) \cdot x_1(2 - x_1)(1 - x_2)(2 - x_2) +$$
$$+ f(1, 1) \cdot x_1(2 - x_1)(2 - x_2) +$$
$$+ f(1, 2) \cdot x_1(1 - x_1)(1 - x_2)(1 - x_2) +$$
$$+ f(2, 0) \cdot \frac{1}{2}(-x_1)(1 - x_1)(1 - x_2)(2 - x_2) +$$
$$+ f(2, 1) \cdot \frac{1}{2}(-x_1)(1 - x_1)(2 - x_2) +$$
$$+ f(2, 2) \cdot \frac{1}{4}(-x_1)(1 - x_1)(2 - x_2)(1 - x_2).$$

E.g., for the 3-valued function $f(x_1, x_2) = \text{MIN}(x_1, x_2)$, the corresponding polynomial is

$$A_3[f](x_1, x_2) = x_1(2 - x_1)x_2(2 - x_2) + x_1(1 - x_1)(2 - x_2)(1 - x_2) +$$
$$+ (x_2)(1 - x_1)x_2(2 - x_2) + 2(-x_1)(1 - x_1)(-x_2)(1 - x_2)$$

$$= \frac{1}{2}x_1x_2 - x_1x_2 - x_1x_2 + \frac{3}{2}x_1x_2.$$

Note that the $A$-transform is defined only for assignments $(b_1, \ldots, b_n) \in M^n$. Therefore, if two field functions $f_z$ and $g_z$ have the same values for all $(b_1, \ldots, b_n) \in M^n$, then they are treated identically by the $A$-transform. We say that two such functions are $m$-equivalent.
Definition 4 The functions \( f_z \) and \( g_z \) of type \( \mathbb{Z}_p^m \to \mathbb{Z}_p \) are m-equivalent if and only if
\[
f_z(b_1, \ldots, b_n) = g_z(b_1, \ldots, b_n)
\]
for any assignment \((b_1, \ldots, b_n) \in M^n\).

We write \( f_z \equiv_m g_z \) to denote that \( f_z \) and \( g_z \) are m-equivalent. If both \( f \) and \( g \) are multiple-valued functions of type \( M^n \to M \) then \( f \equiv_m g \) is the same as \( f = g \).

By Definition 3, \( f_z \equiv_m g_z \) implies \( A_m[f_z] = A_m[g_z] \). However, can we conclude \( A_m[f_z] \neq A_m[f_z] \) from \( f_z \neq g_z \)? To answer this question let us examine the behavior of polynomial \( A_m[f] \) when it is evaluated for some assignment \((b_1, \ldots, b_n) \in M^n\). It is easy to see that for any \( b, b' \in M \), \( w(b, b') = 1 \) if \( b = b' \), and \( w(b, b') = 0 \) otherwise. Therefore, for any \((b_1, \ldots, b_n), (b'_1, \ldots, b'_n) \in M^n\), \( W(b_1, \ldots, b_n, b'_1, \ldots, b'_n) = 1 \) if \( b_i = b'_i \) for all \( i \in \{1, \ldots, n\} \), and \( W(b_1, \ldots, b_n, b'_1, \ldots, b'_n) = 0 \) otherwise. Using these facts, we can prove the following theorem:

Theorem 1 For any function \( f_z : \mathbb{Z}_p^m \to \mathbb{Z}_p \), \( A_m[f_z] \equiv_m f_z \).

Proof: By Definition 3, for any \((b_1, \ldots, b_n) \in M^n\) we have:
\[
A_m[f_z](b_1, \ldots, b_n) = \sum_{(b_1', \ldots, b_n') \in M^n} f_z(b_1, \ldots, b_n) \cdot W_n(b_1, \ldots, b_n, b_1', \ldots, b_n').
\]
Since \( W(b_1, \ldots, b_n, b_1', \ldots, b_n') = 1 \) only if \( b_i = b'_i \) for all \( i \in \{1, \ldots, n\} \), and 0 otherwise, this gives us \( A_m[f_z](b_1, \ldots, b_n) = f(b_1, \ldots, b_n) \cdot 1 \). Since it holds for any \((b_1, \ldots, b_n) \in M^n\), we get \( A_m[f_z] \equiv_m f_z \).

\( \square \)

It follows from the theorem that, though applying the A-transform to a multiple-valued function \( f \) increases the domain of \( f \) from \( M^n \) to \( \mathbb{Z}_p^m \), the polynomial \( A_m[f] \) still yields the same values as \( f \) when evaluated for an assignment \((b_1, \ldots, b_n) \in M^n\). Therefore, the polynomials for two different multiple-valued functions \( f \) and \( g \) differ on all assignments \((b_1, \ldots, b_n) \in M^n\) for which \( f(b_1, \ldots, b_n) \neq g(b_1, \ldots, b_n) \). Consequently, \( f \neq g \) implies \( A_m[f] \neq A_m[g] \).

3 Computing the A-transform

Computing A-transforms using Definition 3 is feasible for very small functions. For larger functions, we develop an alternative method, which is described in this section.

Let \( f_{x_i=j} \) denotes a subfunction of the function \( f(x_1, \ldots, x_n) \) with the variable \( x_i \) being fixed to the value \( j \), i.e. \( f_{x_i=j} \equiv f(x_1, \ldots, x_{i-1}, j, x_{i+1}, \ldots, x_n) \).

We can apply to a polynomial \( A_m[f] \) the following decomposition, which can be considered as a generalization of Shannon decomposition of Boolean functions:

Theorem 2 Every polynomial \( A_m[f] \), \( m > 1 \), can be decomposed with respect to a variable \( x_i \) of \( f \), \( i \in \{1, \ldots, n\} \), in the following way
\[
A_m[f] = \sum_{j=0}^{m-1} \left( \prod_{k \in M^m(j)} \frac{k-x_i}{k-j} \right) \cdot A_m[f_{x_i=j}]
\]
\textbf{Proof:} In order to simplify the exposition and without loss of generality, we show the proof for the case of \( x_i = x_1 \):

\[
A_m[f] = \sum_{(b_1, \ldots, b_n) \in M^n} f(b_1, \ldots, b_n) \cdot W_n(b_1, \ldots, b_n, x_1, \ldots, x_n) \quad \text{(Def. 3)}
\]

\[
= \sum_{j=0}^{m-1} \sum_{(b_1, \ldots, b_n) \in M^{n-1}} f(j, b_2, \ldots, b_n) \cdot W_n(j, b_2, \ldots, b_n, x_1, \ldots, x_n) \quad \text{(re-grouping)}
\]

\[
= \sum_{j=0}^{m-1} \sum_{(b_1, \ldots, b_n) \in M^{n-1}} f(j, b_2, \ldots, b_n) \cdot \left( \prod_{k \in M \setminus \{j\}} \frac{k-j}{k-j} \right) \cdot W_{n-1}(b_2, \ldots, b_n, x_2, \ldots, x_n)
\]

\[
\{w(j, x_1) = \prod_{k \in M \setminus \{j\}} \frac{k-j}{k-j}, \text{ Def. 2} \}
\]

\[
= \sum_{j=0}^{m-1} \left( \prod_{k \in M \setminus \{j\}} \frac{k-j}{k-j} \right) \cdot A_m[f_{x_1=j}]
\quad \text{(Def. 3)}
\]

Next, we prove a lemma showing how that term \( \prod_{k \in M \setminus \{j\}} \frac{k-j}{k-j}, \ j \in M \), can be expressed by an \( m \)-equivalent polynomial in linear form.

\textbf{Lemma 1} \( \text{For any variable } x, \text{ from } \mathbb{Z}_p, \text{ any fixed } j \in M, \text{ and } m > 2: \)

\[
\prod_{k \in M \setminus \{j\}} \frac{k-x}{k-j} = \begin{cases} 
\sum_{i=0}^{m-1} a_i x^i & \text{if } j = 0 \\
 a_{j,i} x^i + a_{j(m-j)} x^{m-j} & \text{if } j \in M \setminus \{0\} \text{ and } j \neq m-j \\
a_{j,i} x^i & \text{if } j \in M \setminus \{0\} \text{ and } j = m-j
\end{cases}
\]

where \( \forall i, j \in M, \ a_{ij} = D_{ij}^2 \), with \( D \) and \( D_{ij} \) given by

\[
D = \sum_{i=1}^{m-1} x^i - \sum_{i=1}^{m-1} x^{(m-i)}
\]

\[
D_{ij} = \begin{cases} 
\prod_{k=1}^{m-1} k^{k \oplus m} - \prod_{k=1}^{m-1} k^{(m-k) \oplus m} & \text{if } j = 0 \\
\frac{1}{x^j} \cdot \prod_{k=1}^{m-1} k^k & \text{if } j 
eq 0 \text{ and } j = i \text{ and } j \neq m-i \quad \text{(1)} \\
\frac{1}{x^{m-j}} \cdot \prod_{k=1}^{m-1} k^{m-k} & \text{if } j 
eq 0 \text{ and } j = m-i \text{ and } j \neq i \\
\frac{1}{x^j} \left( \prod_{k=1}^{m-1} k^k - \prod_{k=1}^{m-1} k^{m-k} \right) & \text{if } j 
eq 0 \text{ and } j = i \text{ and } j = m-i \\
0 & \text{otherwise}
\end{cases}
\]

where \( \oplus_m \) denotes addition modulo \( m \) and all other operations are regular arithmetic operations in \( \mathbb{Z}_p \).
**Proof:** We compute the coefficients \( a_{ij}, \ i, j \in M \), by solving the following system of \( m \) linear equations with \( m \) unknown elements:

\[
\begin{align*}
    a_{0j} \cdot 0^0 + a_{1j} \cdot 0^1 + a_{2j} \cdot 0^2 + \cdots + a_{(m-1)j} \cdot 0^{m-1} &= b_0 \\
    a_{0j} \cdot 1^0 + a_{1j} \cdot 1^1 + a_{2j} \cdot 1^2 + \cdots + a_{(m-1)j} \cdot 1^{m-1} &= b_1 \\
    a_{0j} \cdot 2^0 + a_{1j} \cdot 2^1 + a_{2j} \cdot 2^2 + \cdots + a_{(m-1)j} \cdot 2^{m-1} &= b_2 \\
    \vdots \\
    a_{0j} \cdot (m-1)^0 + a_{1j} \cdot (m-1)^1 + a_{2j} \cdot (m-1)^2 + \cdots + a_{(m-1)j} \cdot (m-1)^{m-1} &= b_{m-1}
\end{align*}
\]

where \( \forall i \in M, \ b_i = \prod_{k \in M - \{j\}} \frac{k-1}{k-j} \). Such a system can be described by matrices as \( X \cdot a = b \), where

\[
X = \begin{pmatrix}
0^0 & 0^1 & 0^2 & \cdots & 0^{m-1} \\
1^0 & 1^1 & 1^2 & \cdots & 1^{m-1} \\
2^0 & 2^1 & 2^2 & \cdots & 2^{m-1} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
(m-1)^0 & (m-1)^1 & (m-1)^2 & \cdots & (m-1)^{m-1}
\end{pmatrix},
\]

\[
a = \begin{pmatrix}
a_{0j} \\
a_{1j} \\
a_{2j} \\
\vdots \\
a_{(m-1)j}
\end{pmatrix}, \quad b = \begin{pmatrix}
b_0 \\
b_1 \\
b_2 \\
\vdots \\
b_{m-1}
\end{pmatrix}.
\]

From linear algebra we know that such a system always has a solution, and this solution is unique [9]. We compute the \( i \)-th element of \( a \) by applying Kramer's rule, which says that, for any \( i \in M \), \( a_{ij} \) is given by the formula \( a_{ij} = \frac{D_{ij}}{D} \), where \( D \) is the determinant of \( X \), and \( D_{ij} \) is the determinant computed after the replacement of the \( i \)-th column of \( X \) by vector \( b \).

Observe, that matrix \( X \) has a very regular structure, namely for all \( i, j \in M, \ x_{ij} = i^j \). Therefore, by applying standard rules for computing determinants [9], it is easy to show that \( D \) and \( D_{ij} \) are given by the equation (1).

Examining the structure of \( D_{ij} \), we can derive the following properties of the elements of \( a_{ij} \):

\[
a_{ij} = \begin{cases} 
    \frac{D_{ij}}{D} & \text{for } \forall i, j : \text{such that } j = 0 \text{ or } i = j \text{ or } i = m - j \\
    0 & \text{otherwise}
\end{cases} \tag{2}
\]

So, the only elements \( a_{ij} \) which can possibly have non-zero values are \( a_{i0} \) for all \( i \in M \), and \( a_{jj} \) and \( a_{j(m-j)} \) for all \( j \in M - \{0\} \). Therefore, the expression for the term \( \prod_{\forall k \in M - \{j\}} \frac{k-x}{k-j} \) can be simplified to:

\[
\prod_{\forall k \in M - \{j\}} \frac{k-x}{k-j} = \begin{cases} 
    \sum_{i=0}^{m-1} a_{i0} x^i & \text{if } j = 0 \\
    a_{jj} x^j + a_{j(m-j)} x^{m-j} & \text{if } j \in M - \{0\} \text{ and } j \neq m - j \\
    a_{jj} x^j & \text{if } j \in M - \{0\} \text{ and } j = m - j
\end{cases}
\]

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As we mentioned above, \( \prod_{j \in M \setminus \{j\}} \frac{x^j}{k_j} \) has a behavior similar to the behavior of the literal operator \( \hat{\cdot} \), except that for \( x = j \) the literal \( \hat{\cdot} \) evaluates to \( m - 1 \), and not to 1. Therefore, \( \hat{\cdot} \equiv (m - 1) \cdot \prod_{j \in M \setminus \{j\}} \frac{x^j}{k_j} \), and thus, from Lemma 1, we can conclude that

\[
\hat{\cdot} \equiv \begin{cases} 
(m - 1) \cdot \sum_{j=0}^{m-1} a_{0j} x^j & \text{if } j = 0 \\
(m - 1) \cdot (a_{jj} x^j + a_{j(m-j)} x^{m-j}) & \text{if } j \in M \setminus \{0\} \text{ and } j \neq m - j \\
(m - 1) \cdot a_{jj} x^j & \text{if } j \in M \setminus \{0\} \text{ and } j = m - j 
\end{cases}
\]

We use Theorem 2 and Lemma 1 to derive another type of decomposition of \( A_m[f] \), which will be used later to derive a canonical expansion for \( A_m[f] \). Before giving the decomposition, we first summarize some properties of \( A_m[f] \), obvious from Definition 3.

**Lemma 2** For any field functions \( f_z \) and \( g_z \) and any constant \( c \in \mathbb{Z}_p \),

(a) \( A_m[c \cdot f_z] = c \cdot A_m[f_z] \).

(b) \( A_m[f_z + g_z] = A_m[f_z] + A_m[g_z] \).

**Theorem 3** Every polynomial \( A_m[f], m > 1 \), can be decomposed with respect to a variable \( x \) of \( f \) in the following way:

**case 1:** if \( m \) is odd, then

\[
A_m[f] = a_{00} A_m[f_{x=0}] + \sum_{j=1}^{m-1} \left( (a_{j0} A_m[f_{x=0}] + a_{jj} A_m[f_{x=j}] + a_{j(m-j)} A_m[f_{x=m-j}]) \cdot x^j \right)
\]

**case 2:** if \( m \) is even, then

\[
A_m[f] = a_{00} A_m[f_{x=0}] + \sum_{j=1}^{m-1} \left( (a_{j0} A_m[f_{x=0}] + a_{jj} A_m[f_{x=j}] + a_{j(m-j)} A_m[f_{x=m-j}]) \cdot x^j + \right.
\]

\[
+ \left. (a_{m0} A_m[f_{x=0}] + a_{m(m/2)} A_m[f_{x=m/2}]) \cdot x^{m/2} \right)
\]

where \( \forall i, j \in M, a_{ij} = \frac{D_{ij}}{D_{jj}} \), and \( D \) and \( D_{ij} \) given by (1).

**Proof:**

\[
A_m[f] = \sum_{j=0}^{m-1} \left( \prod_{k \in M \setminus \{j\}} \frac{x^j}{k_j} \right) \cdot A_m[f_{x=k}] \quad \{\text{Theorem 2}\}
\]

\[
= \sum_{j=0}^{m-1} a_{0j} x^j \cdot A_m[f_{x=0}] + \sum_{j=1}^{m-1} (a_{jj} x^j + a_{j(m-j)} x^{m-j}) \cdot A_m[f_{x=j}] \quad \{\text{Lemma 1}\}
\]

\[
= a_{00} A_m[f_{x=0}] + \sum_{j=1}^{m-1} (a_{j0} A_m[f_{x=0}] + a_{jj} A_m[f_{x=j}] + a_{j(m-j)} A_m[f_{x=m-j}]) \cdot x^j
\]

\{reordering\}
Let $F$ be the vector of coefficients of the truth table of the function $f$ and $A^n$ be a transformation matrix, defined as follows:

**Definition 5** The $m^n \times m^n$ matrix $A^n$ is defined inductively by:

1. $A^1 \overset{df}{=} \begin{bmatrix} a_{00} & 0 & 0 & \ldots & 0 & 0 \\ a_{10} & a_{11} & 0 & \ldots & 0 & a_{1(m-1)} \\ a_{20} & 0 & a_{22} & \ldots & a_{2(m-2)} & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{(m-2)0} & 0 & a_{(m-2)2} & \ldots & a_{(m-2)(m-2)} & 0 \\ a_{(m-1)0} & a_{(m-1)1} & 0 & \ldots & 0 & a_{(m-1)(m-1)} \end{bmatrix}$

where $\forall i, j \in M$, the coefficients $a_{ij}$ are given by (2).

2. $A^n \overset{\otimes}{=} A^1 \otimes A^{n-1}$

where "$\otimes$" denotes the Kronecker product of two matrices.

Clearly, if Theorem 3 is successively applied to the polynomials $A_m[f_{x_i=k}]$ of subfunctions $f_{x_i=k}$ about all the remaining variables, we will finally get an expression in which $A_m[f]$ is expanded in all the variables of $f$:

**Theorem 4** Every polynomial $A_m[f]$, $m > 2$, of an $n$-variable $m$-valued function $f$ can be expressed in the following canonical form

$$A_m[f] = \sum_{j=0}^{m^n-1} c_j \cdot x_1^{i_1} \cdot x_2^{i_2} \cdot \ldots \cdot x_n^{i_n}$$

where $(i_1, i_2, \ldots, i_n)$ is the $m$-ary expansion of $i$, with $i_1$ being the least significant digit, and the coefficients $c_i$ are given by the vector $C \overset{df}{=} [c_0, c_1, \ldots, c_{m^n-1}]$ computed as $C = A^n \cdot F$.

**Proof:** By induction on $n$. We show the proof only for the case of $m$ being odd. For $m$ even the proof is similar.

1) Let $n = 1$. According to Theorem 3, any polynomial $A_m[f]$ of a function $f(x)$ of one variable $x$ can be decomposed with respect to $x$ as:

$$A_m[f] = a_{00} \cdot A_m[f_{x=0}] + \sum_{j=1}^{m-1} (a_{0j} \cdot A_m[f_{x=0}] + a_{jj} \cdot A_m[f_{x=j}] + a_{j(m-j)} \cdot A_m[f_{x=m-j}]) \cdot x^j$$

where $f_{x=k} = f(k)$. By Lemma 2, $A_m[c] = c$ for any constant $c \in \mathbb{Z}_m$. So, we can express the above as:

$$A_m[f] = a_{00} \cdot f(0) + \sum_{j=1}^{m-1} (a_{0j} \cdot f(0) + a_{jj} \cdot f(j) + a_{j(m-j)} \cdot f(m-j)) \cdot x^j$$

$$8$$
which can be re-written as

\[ A_m[f] = \sum_{i=0}^{m-1} c_i x^i \]

where \( c_0 = a_{00} \cdot f(0) \) and \( c_j = a_{0j} \cdot f(0) + a_{jj} \cdot f(j) + a_{j(m-j)} \cdot f(m-j) \), for all \( j \in M - \{0\} \).

Examining the structure of the matrix \( A^1 \), we can conclude that \( C = A^1 \cdot F \).

2) Hypothesis: Assume the result for \( n \). According to Theorem 3, any \( A_m[f] \) of a function \( f \) of \( n + 1 \) variables can be decomposed with respect to \( x_{n+1} \) in the following way:

\[ A_m[f] = a_{00} A_m[f_{x_0=0}] + \sum_{j=1}^{m-1} (a_{0j} A_m[f_{x=j}] + a_{jj} A_m[f_{x=j}] + a_{j(m-j)} A_m[f_{x=m-j}]) \cdot x_{n+1}^j \]

By the induction hypothesis, we can express each \( A_m \) of the subfunctions of \( n \) variables in the canonical form. We use the notation \( c_i^j \) to denote the \( i \)th coefficient of the canonical form of the subfunction \( f_{x_{n+1}=k} \) and \( F_k \) for the truth table vector of \( f_{x_{n+1}=k} \). To simplify the exposition we also use the abbreviation \( X \) to stand for the term \( x_{n+1}^1 \cdot x_{n+1}^2 \cdots x_{n+1}^n \). So, we replace each of \( A_m[f_{x_{n+1}=k}] \), \( k \in M \), by \( \sum_{i=0}^{m-1} c_i^k \cdot X \), with \( c_i^k \) given by \( C_k = A^n \cdot F_k \). Then we get:

\[ A_m[f] = a_{00} \cdot \sum_{i=0}^{m-1} c_i^0 \cdot X + \sum_{j=1}^{m-1} \left( a_{0j} \cdot \sum_{i=0}^{m-1} c_i^j \cdot X + a_{jj} \cdot \sum_{i=0}^{m-1} c_i^j \cdot X + a_{j(m-j)} \cdot \sum_{i=0}^{m-1} c_i^{m-j} \cdot X \right) \cdot x_{n+1}^j \]

Since "*" is distributive over "+", we can re-order the above as

\[ A_m[f] = \left( \sum_{i=0}^{m-1} a_{00} \cdot c_i^0 \cdot X \right) \cdot x_{n+1}^0 + \sum_{j=1}^{m-1} \left( \sum_{i=0}^{m-1} \left( a_{0j} \cdot c_i^j + a_{jj} \cdot c_i^j + a_{j(m-j)} c_i^{m-j} \right) \cdot X \right) \cdot x_{n+1}^j \]

which can be re-written as

\[ A_m[f] = \sum_{j=0}^{m-1} c_j \cdot x_{n+1}^i \cdot x_{n+1}^2 \cdots x_{n+1}^n \]

where \( c_i = a_{00} \cdot c_i^0 \), for \( 0 \leq i \leq m - 1 \), and \( c_i = a_{0j} \cdot c_i^j + a_{jj} \cdot c_i^j + a_{j(m-j)} c_i^{m-j} \), for \( j \cdot m \leq i \leq j \cdot m + m - 1 \), for all \( j \in M - \{0\} \). Since the coefficients \( c_i^j \) are given by \( C_j = A^n \cdot F_j \), this is equivalent to \( C = (A^1 \otimes A^n) \cdot F = A^{n+1} \cdot F \).

\[ \square \]

For example, for \( m = 3 \) and \( n = 2 \), the matrix \( A^2 \) is constructed as follows:

\[ A^1 = \begin{bmatrix} 1 & 0 & 0 \\ -3/2 & 2 & -1/2 \\ 1/2 & -1 & 1/2 \end{bmatrix} \]
and

\[
A^2 = \begin{bmatrix}
1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
-3/2 & 2 & -1/2 & 0 & 0 & 0 & 0 & 0 \\
1/2 & -1 & 1/2 & 0 & 0 & 0 & 0 & 0 \\
-3/2 & 0 & 0 & 2 & 0 & 0 & -1/2 & 0 \\
1/2 & 0 & 0 & -1 & 0 & 0 & 1/2 & 0 \\
1/4 & -1/2 & 1/4 & -1/2 & 1 & -1/2 & 1/4 & -1/2 \\
1/4 & -1/2 & 1/4 & -1/2 & 1/4 & -1/2 & 1/4 & -1/2 \\
\end{bmatrix}
\]

So, we can compute \( A_3[f] \) for \( f = \text{MIN}(x_1, x_2) \), as \( C = A^2 \cdot F = \)

\[
\begin{bmatrix}
1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
-3/2 & 2 & -1/2 & 0 & 0 & 0 & 0 & 0 \\
1/2 & -1 & 1/2 & 0 & 0 & 0 & 0 & 0 \\
-3/2 & 0 & 0 & 2 & 0 & 0 & -1/2 & 0 \\
1/2 & 0 & 0 & -1 & 0 & 0 & 1/2 & 0 \\
1/4 & -1/2 & 1/4 & -1/2 & 1 & -1/2 & 1/4 & -1/2 \\
\end{bmatrix}
\begin{bmatrix}
0 \\
0 \\
0 \\
0 \\
1 \\
1 \\
1 \\
2 \\
1/2 \\
\end{bmatrix}
= \begin{bmatrix}
5/2 \\
0 \\
0 \\
0 \\
0 \\
0 \\
0 \\
0 \\
\end{bmatrix}
\]

Thus, \( A_3[f](x_1, x_2) = \frac{5}{2}x_1x_2 - x_1x_1^2 - x_1^2x_2 + \frac{1}{2}x_1^2x_2^2 \).

### 4 Computing hash code of the function

We compute the hash code of the function \( f \) by assigning randomly chosen integer values from \( \mathbb{Z}_p \) to the input variables of \( f \), and then evaluating \( A_m[f] \) for this values. The resulting number is the integer hash code \( C \) of \( f \). This code requires less space than the canonical MDD representation of the same function and distinguishes any pair of multiple-valued functions with a quantifiable probability of success. The hash codes for two equivalent functions are always the same. Thus, the equivalence of two functions can be verified with a known probability of error, which arises from collisions between inequivalent functions.

For example, consider the 3-valued 3-variable function \( f = \text{MIN}(x_1, x_2) \) and let the variables be assigned the random values \( x_1 = 2, x_2 = 4 \). Since \( A_3[f] = \frac{5}{2}x_1x_2 - x_1x_1^2 - x_1^2x_2 + \frac{1}{2}x_1^2x_2^2 \), the hash code for \( f \) is 4.

As another example, consider the function \( g = \text{MAX}(\text{MIN}(2, x_1, x_2), \text{MIN}(1, x_1, x_2)) \). Since \( A_3[g] = -2x_1 + 2x_1x_2 - \frac{1}{2}x_1x_2^2 + 2 - 2x_1^2x_2 + \frac{1}{2}x_1^2x_2^2 \), if we assign \( x_1 = 2 \) and \( x_2 = 4 \) we obtain the same hash code 4 as for \( \text{MIN} \) function and therefore get collision between two inequivalent functions.

However, we can considerably decrease the probability of collision by making multiple runs. On each run, an independent set of input variable assignment is randomly chosen, and the two function values are computed. If the values differ, we are assured that the two functions are not the same. If they are equal, we choose a new set of input assignments and re-evaluate.
The probability of erroneously deciding that the functions are equal decrease exponentially with the number of runs: after \( k \) runs, the error probability is \( \varepsilon^k \). For example, if we make a second run for the functions specified above, with the random values \( x_1 = 3 \) and \( x_2 = 1 \), then the hash code for \( \text{MIN} \) function is 0 and hash code for \( g \) function is 3. So, we can conclude that \( f \neq g \).

5 Conclusion

This paper lays a theoretical foundation of a probabilistic method for verification of multiple-valued functions. We define a functional transformation, which is can be used to obtain an integer code from a multiple-valued function. The integer codes allow us to determine probabilistically whether two functions are equivalent.

Further research remains designing an efficient procedure for computing integer hash codes. A simple way to compute a hash code would be to build an MDD or similar structure from the input function and then apply a procedure for reducing this structure to an appropriate integer. Of course, the efficiency of such a scheme would be limited by the need to create and evaluate an MDD representation of the entire function. A better approach, which we are currently pursuing, is first to symbolically decompose the function, and then hash it incrementally. This can be done by first hashing some of its parts, and then using these more compact intermediate forms to complete the hashing of the entire function.

Another open problem is estimating a bound on the probability that two inequivalent multiple-valued functions map to the same integer code. In Boolean case, a lower bound on the probability that a random \( m \)-variable vector from \( Z_2 \) distinguishes a given pair of Boolean functions is shown to be \( \left( \frac{2^{m-1}}{m} \right)^n \) [8], but generalizing this result to \( m \)-valued case is a non-trivial problem.

References


