

Implementation of Feedback Mechanism into AODV based on NS2

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Abstract

This paper gives an overview on the implementation of a feedback mechanism into the AODV routing protocol based on NS2. This implementation work was done as part of seminar called *Attacks And Security Strategies in Mobile And Ad-hoc Networks*. The requirements of that project will be determined and the specific implementation details will be discussed afterwards. Some detailed information on NS2(e.g. structure, AODV and Scheduler) will be described as well, as it is necessary for understanding.

1 Introduction

The main goal of this project was the implementation of a feedback mechanism described in the paper *Feedback-based Solution for Avoiding Attacks on Mobile Ad-Hoc Networks*[1]. This implementation should be used for simulation of this mechanism in virtual ad-hoc networks via the well known simulation software *NS2*. The simulation results should be used for evaluation of that mechanism, e.g. in time overhead or data overhead issues.

2 Requirements

This chapter describes the required steps to achieve the described goal. The main subtasks to achieve this goal are:

- Implementation of feedback mechanism
- Implementation of malicious node behavior
- Implementation of simulation evaluation
- Development and Implementation of specific network simulations

The implementation of the feedback mechanism itself should be done on the routing layer. The mechanism itself works directly on the routing layer. It discovers malicious behavior on the routing layer. It sends additional messages that directly affect the behavior on the routing layer, e.g. no routing over untrusted or malicious nodes. The implementation can be done by modification of existing routing implementation; e.g. AODV. This will be described in section 4 of this paper.

The implementation of the malicious node behavior can be done on different layers, because of the different attack scenarios and vulnerabilities. In this specific example only one attack on routing layer is discussed. An malicious node performing an attack is expected here as a network node with selfish behavior. This node for example does not route packets from other nodes, but drops them. Based on this understanding of an attack, the implementation of the malicious node behavior should be done on the routing layer. The implementation can also be done by modification of existing routing implementation; e.g. AODV.

The implementation of the simulation evaluation can be done in a separate application apart from NS2. This application needs to read NS2 simulation output files, to analyze them and to visualize the results. This will not be described within this paper.

All the implementation work is tested with specific NS2 simulation scripts. These scripts are based on TCL and describes the simulation itself; e.g. the size of the simulation area, the number of the nodes within the area and the number and type of the packets send during this simulation. A useful documentation of NS2 simulation scripts is NS-By-Example[2].

3 Technical Background on NS2

This section describes the technical background of the implementation work. It covers specific parts of the NS2 implementation. More precisely an overview over NS2 is provided, the functionality of the scheduler and the implementation of the AODV implementation will be described. The basis for this implementation is NS2 version 2.30. The implementation is done with the NS2 all-in-one package[3, 4]. The information provided in this section can be found within documentation and the source code. The investigations of AODV protocol functionality are made by NS2 debugging[5].

3.1 Structure

3.1.1 Class Hierarchies

NS2 is a network simulator written in C++ and TCL. The NS2 front end is an OTCL interpreter. The simulation descriptions are scripts written in OTCL. The front end interprets this files and the back end simulates the described scenario. The NS2 simulation output files are generated within this process. Within NS2 there are two separate class hierarchies; the *Compiled Hierarchy*

implemented in C++ and the *Interpreted Hierarchy* implemented in TCL. Furthermore there are classes that realize the processing of the simulation and there are classes that belong to the simulation itself. Within this document objects based on classes that realize the processing of the simulation are called *Processing Objects*. The Objects based on the classes that belong to the simulation itself will be called *Simulation Objects*. Most of the Processing Objects are implemented in the Compiled Hierarchy. For most of the Simulation Objects, there is 1:1 relationship between a base class in the Compiled Hierarchy and a base class in the Interpreted Hierarchy. The implementation of this classes is often separated in two parts, one located in the Compiled Hierarchy and one located in the Interpreted Hierarchy. This makes modification of Simulation Objects very complicated.

The separation in two class hierarchies is reasonable for dealing with the trade-off between runtime performance and iteration time; which means the required time to change the simulation descriptions and execute another simulation. The iteration time can be minimized by utilization of simple scripting language with simple syntax. The runtime performance can be optimized by using a compiled language. Therefore the two approaches are combined within NS2 by using OTCL as front end and C++ as back end.

3.1.2 TCL Linkage

The *TCL Linkage* is the communication interface between the implementation of the Simulation Objects on the two class hierarchies; the Compiled Hierarchy and the Interpreted Hierarchy. It realizes the communication between the implementation parts; e.g. the transmission of messages from Compiled Hierarchy into Interpreted Hierarchy and vice versa. The TCL Linkage consists of six important classes:

- Tcl
- TclObject
- TclClass
- TclCommand
- EmbeddedTcl
- InstVar

The functionality of the TCL Linkage is described in chapter 3 of the NS2 documentation[4].

3.1.3 File System Structure

Figure 1 shows the structure of the file system within NS2. Only the directories are shown, that have a meaning for the described implementation.



Figure 1: File System Structure

- The root directory $\sim/ns-allinone-2.30/$ includes the complete NS2 system.
- The TCL interpreter directory $\sim/ns-allinone-2.30/tclcl/$ includes all files related to the TCL interpreter.
- The NS2 simulator directory $\sim/ns-allinone-2.30/ns-2.30/$ includes all files related to the simulator. This includes the class implementations on Compiled Hierarchy and on Interpreted Hierarchy.
- The NS2 Processing Objects directory $\sim/ns-allinone-2.30/ns-2.30/common/$ includes all class implementations on Compiled Hierarchy.
- The NS Processing Objects directory $\sim/ns-allinone-2.30/ns-2.30/tcl/$ includes the class implementations on Interpreted Hierarchy.
- The NS Simulation Objects directory $\sim/ns-allinone-2.30/ns-2.30/tcl/lib/$ includes the class implementations on Interpreted Hierarchy.
- The AODV directory $\sim/ns-allinone-2.30/ns-2.30/aodv$ includes all classes used by AODV implementation.

Figure 2 shows the most important classes in NS2 and can be used as overview.

3.2 Scheduler

The Scheduler is an entity within NS2 responsible for packet transmission. The scheduler is a single instance within the NS2 runtime that collects and transmits

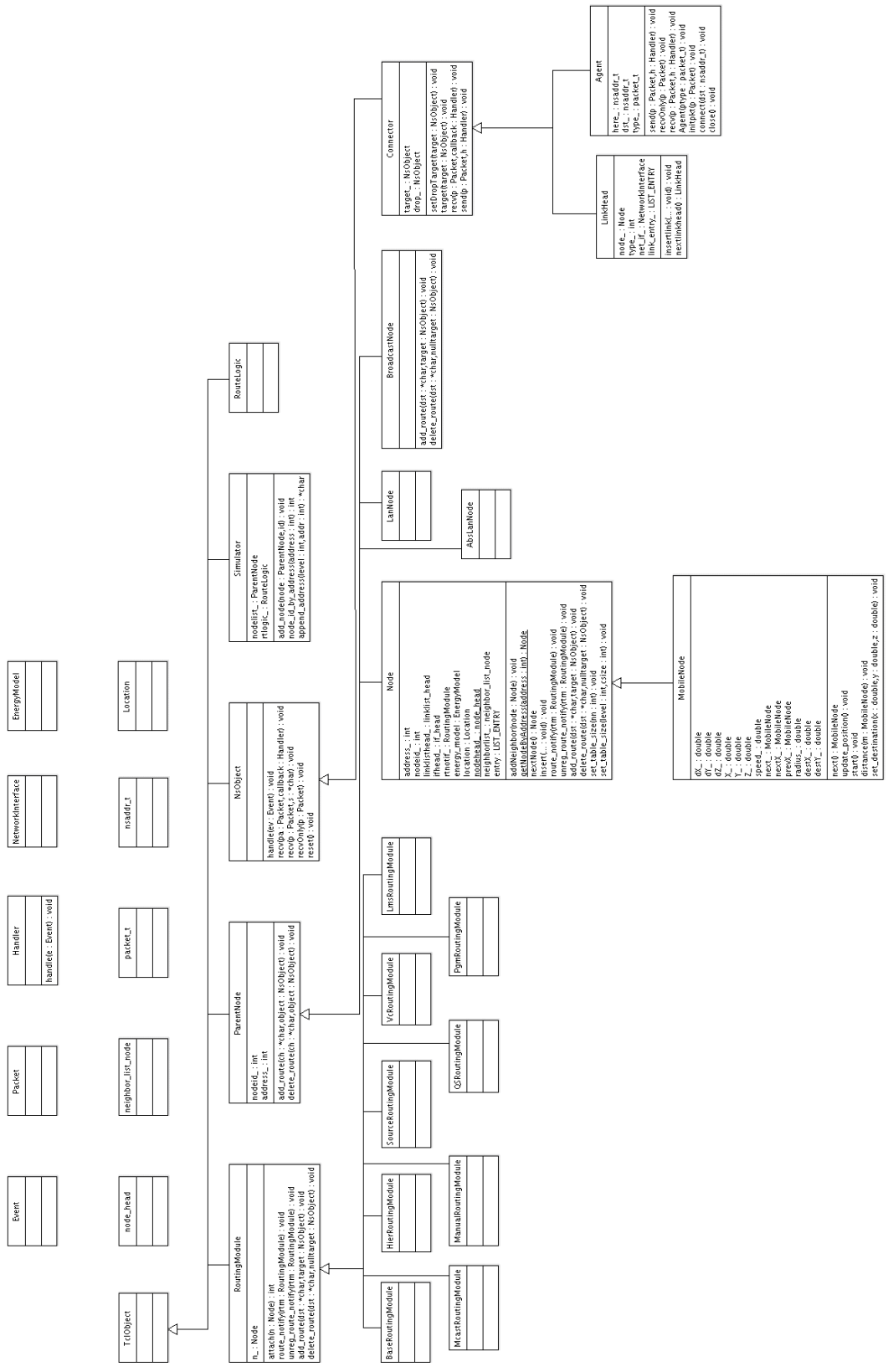


Figure 2: NS2 Class Tree

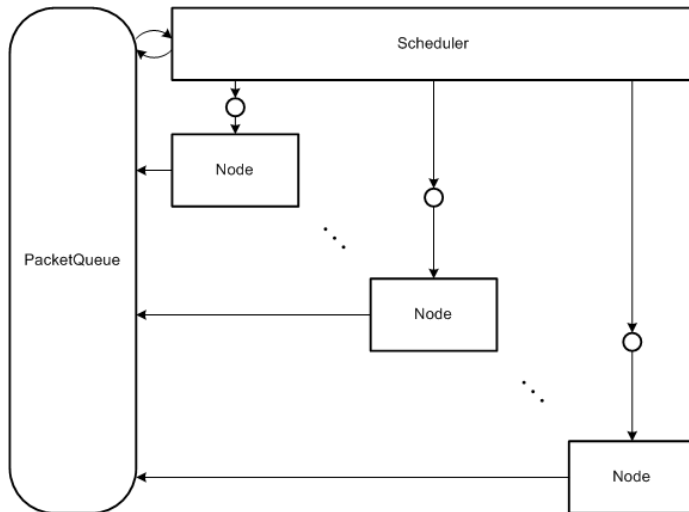


Figure 3: Scheduler

messages. Therefore the Scheduler class is realized as static class with static methods.

Figure 3 shows the logical structure of the scheduler within NS2. The Scheduler consists of control unit and a so called packet queue. This packet queue is accessible through the nodes within the simulation. Each node can put packets into the packet queue. The Scheduler takes each packet from the queue and dispatches the packet to its destination. The process is shown in figure 4. The knows the destination of a packet during runtime. The destination of the packet is saved within a special pointer in the packet structure. This pointer is a reference to a *NSObject* instance where the method *recv()* is called within *Scheduler::dispatch()*.

3.3 AODV Implementation

In mobile and ad-hoc networks there are several routing protocols available; e.g. DSR, DSDV or AODV. Within NS2 there are implementations for some of the available routing protocols. The AODV implementation in NS2 is the basis for the implementation work and is therefore explained in this section. This AODV implementation is not RFC compliant; e.g. there is no implementation for the blacklist defined in AODV[6]. The AODV implementation mainly consists of two functional units.

- Mechanism to detect the route through a network
- Mechanism to forward packets within this route

Figure 5 a simple packet flow within a single node in the simulation. An agent consists to specific node. This agent allocates the packet and initializes the

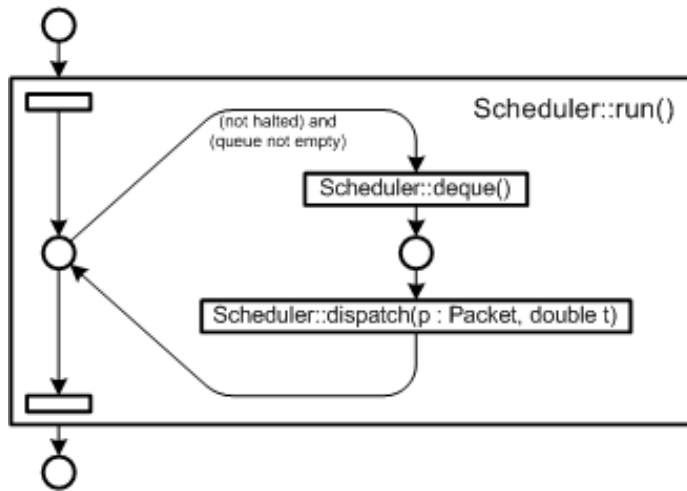


Figure 4: Scheduler Process

content of the packet. Afterwards the packet is handled by the AODV routing mechanism. First the routing handler receives this packet. This is done locally. Afterwards the route for the packet is detected. When a suitable route is found, the packet is forwarded to the next hop within this route. The forward is done by the Scheduler described in section 3.

This figure shows the sequence of calls within the software objects. The call hierarchy in AODV is as follows. The `recv()` method is the first method called. This method calls first the `resolve()` and the `forward()` method. The `forward()` method calls the `Scheduler::scheduler()` method.

Figure 6 shows the initialization process of the AODV implementation in a specific simulation. This simulation consists of three hosts that are located in a line, so that *Host 0* and *Host 2* are not able to communicate directly. Within this simulation one TCP packet is send from *Host 0* to *Host 2* and the reply is send from *Host 2* to *Host 0*. AODV resolves the route to *Host 2* by sending a special *request packet*. This packet is broadcasted as long as the destination of the packet replies. The reply is also broadcasted through the network. Each forwarded request packet also triggers the intermediate nodes to send additional request packets.

Therefore in the beginning of the simulation there is a high amount of AODV related network traffic. After that phase, there is only a few additional AODV network traffic required. Detected routes are cached within this implementation, so that not every send packets requires a related AODV route request. After the detection of the route, the packet is send.

The the packet flow during the transmission is relatively simple. Figure 7 shows the process with the related calls. The packet is forwarded by each node on the route. In the forward method the Scheduler is called, to transmit the packets. The `resolve()` method returns immediately, due to a cached response

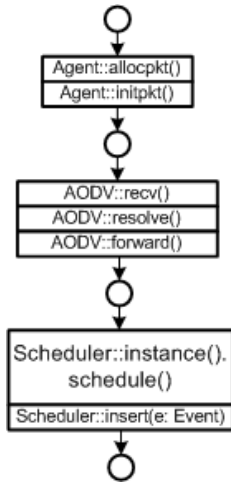


Figure 5: Packet Flow

for the request.

The figure 8 shows the class structure of AODV related classes.

4 Implementation

This sections covers the main ideas of the implementation work. Based on the technical background the implementation is done by modification of the existing mechanisms.

4.1 Feedback Mechanism

This implementation is done by modification of the existing AODV implementation. This implementation is described in section 3.3. To implement the feedback mechanism, the following issues are realized.

The header structure of the common packet is changed. The header `hdr_cmn` is the main header structure utilized for each packet in NS2. The common header is extended with the following information:

```

bool recv_fb_req;
bool one_hop_fb_req;
bool two_hop_fb_req;

int fb_type;
int fb_dst;
int fb_path[PATH_LEN];
  
```

The first three members are boolean values utilized to encode the requested feedback into the packet. Each packet needs to carry information for it's required

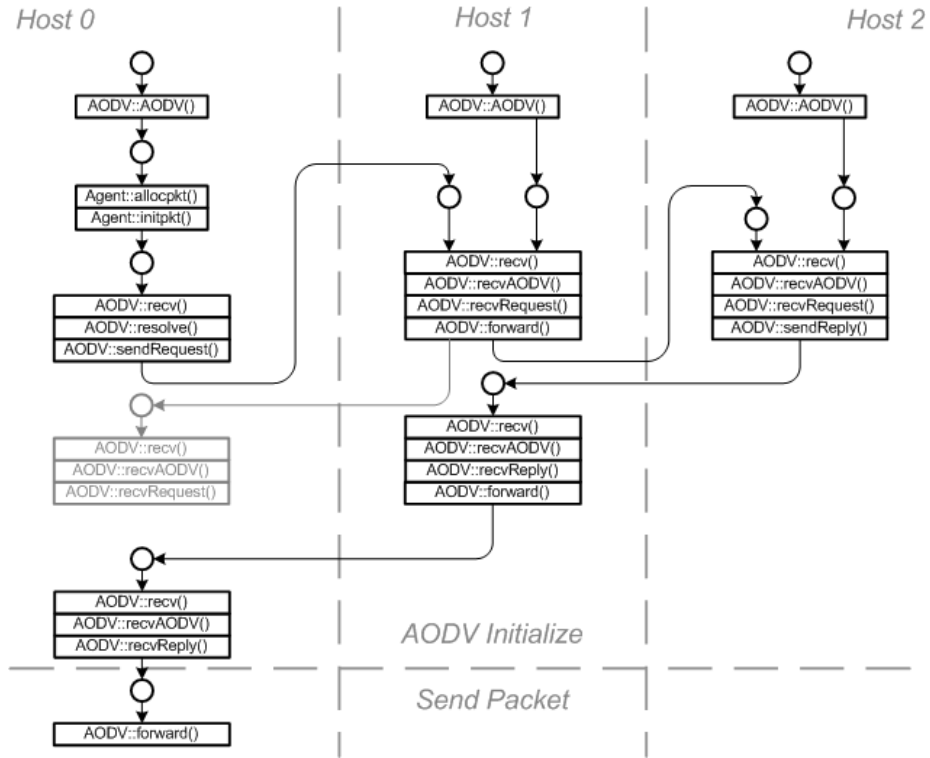


Figure 6: AODV Initialization

feedback. The integer members `fb_type` and `fb_dst` are used for feedback packets to encode the type of the feedback and its destination. The integer `fb_path` array `fb_path` is used to save the feedback route.

Additional packet types are implemented, utilized by nodes to transmit information according to the feedback mechanism. The following packet types are added:

- FB
- FB_REQ
- FB_ACK
- FB_DEV

The FB packet is a general feedback packet. This packet will be sent when a packet is received and a feedback is required. The FB_REQ packet is used to request a feedback of a host that was not sent in time. The FB_ACK packet is used to acknowledge a received feedback. The FB_DEV packet is used to inform neighbor nodes when the reputation of a node is devalued.

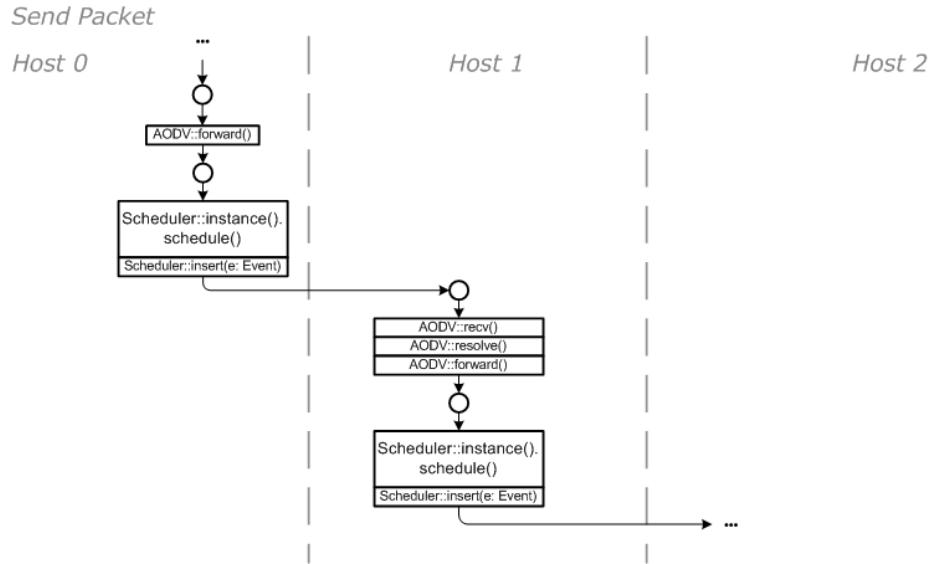


Figure 7: Transmission Packet Flow

Several new data storages are implemented within the class AODV. The following data storages related to the feedback mechanism are implemented:

```

list<ReputationListElement>    repList;
list<ReputationListElement>    sendFeedbackList;
list<ForwardedListElement>     forwardedPacketList;
  
```

The repList is used to save all reputation values of the neighbor nodes. The sendFeedbackList saves all the feedback packets that the node sends. The forwardedPacketList saves all forwarded packets, processed by this host.

To send new types of packets there is a new timeout handler required. This timeout handler get a callback, when he timeout is reached. When there is no feedback acknowledge received yet, the feedback is requested. If this fails, the reputation of the neighbor host, responsible for the feedback, is decreased.

The AODV class is extended with methods to send and receive feedback packets. The following methods are added:

```

void sendFB(Packet *pfb,nsaddr_t dst, int uid,int type);
void sendFBRequest(nsaddr_t dst);
void sendFBBack(nsaddr_t dst);
void sendFBDevalue(nsaddr_t dst);
void rcvFB(Packet *p);
void rcvFBRequest(Packet *p);
void rcvFBBack(Packet *p);
void rcvFBDevalue(Packet *p);
  
```

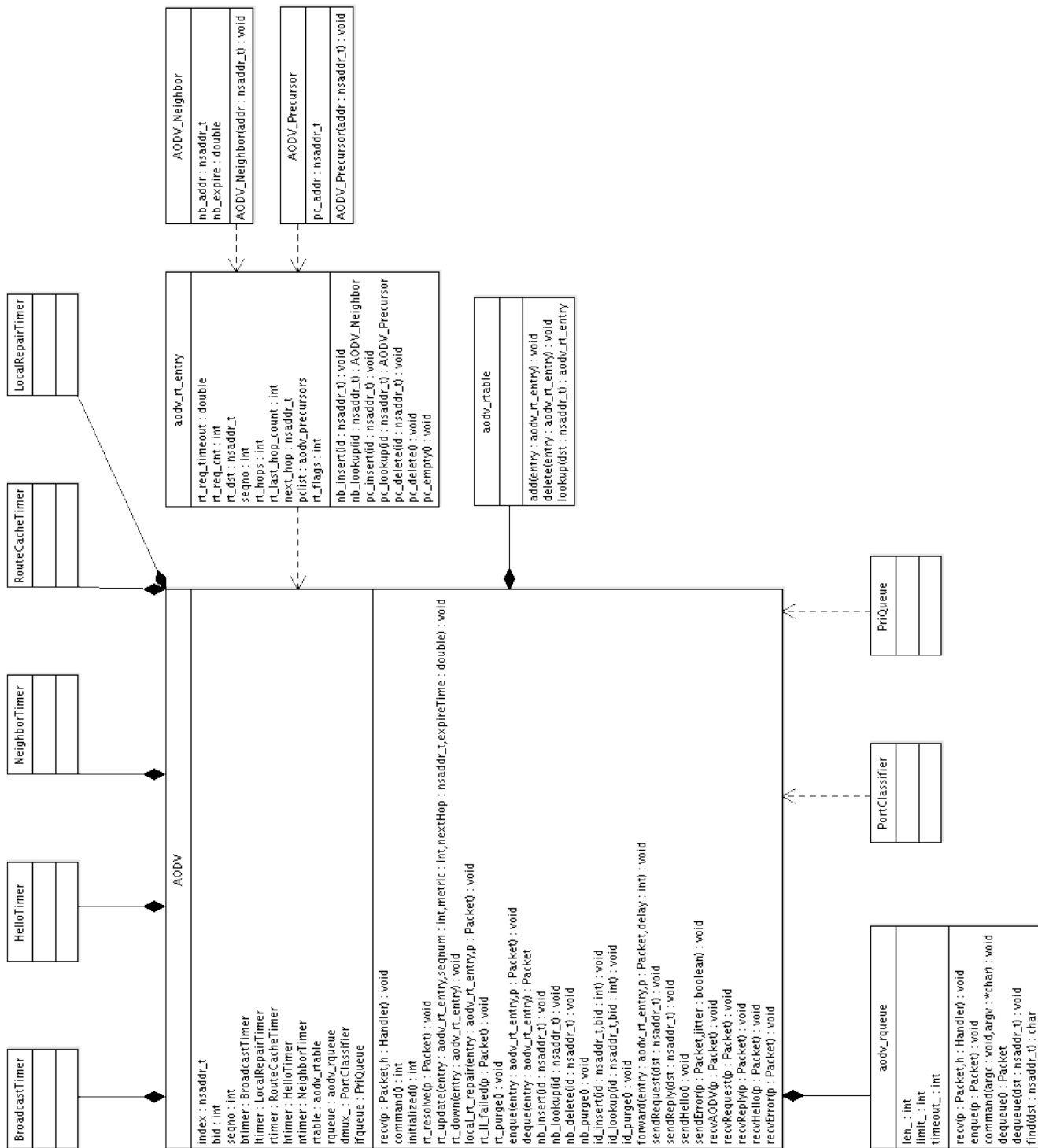


Figure 8: AODV Class Structure

The trace subsystem of NS2 is modified, due to the additional packet types. The new packet types are processed and logged through this logging system.

4.2 Malicious Node Behavior

The malicious node behavior here only covers the packet dropping within the route. It is a selfish behavior of a node to increase its network performance. To implement the attack on the routing layer the AODV forwarding mechanism is modified in the following way.

A node is configured to show malicious behavior through a configuration file. When the AODV object is instantiated the first time, a file is read that includes all malicious node configurations. The AODV class holds a static list to save the node configurations.

```
static list<MaliciousNodeListElement> maliciousNodeList;
```

Each node is configured through the members `badNode` and `dropping_rate`. The boolean member `badNode` holds information whether the node is malicious. The `dropping_rate` member holds the information of the dropping rate of this malicious node.

```
bool badNode;  
int dropping_rate;
```

The nodes configured as malicious nodes are dropping forwardable packets with a specified rate. This is done by modification of the `forward` method within AODV. The dropping of a packet is logged through trace subsystem.

4.3 Blacklist

As described in section 3.3 the AODV implementation is not RFC compliant. The blacklist is needed by the feedback mechanism to avoid detected malicious nodes. The current AODV implementation does not provide a working blacklist. Therefore the blacklist is newly implemented into AODV by modification of the AODV class.

```
list<nsaddr_t> blacklist;
```

The blacklist member is added into the AODV class. Each host listed on the blacklist is excluded from the AODV routing. Request and replies from those hosts are not accepted and the forwarding of packets from this hosts is disabled.

References

- [1] *Feedback-based Solution for Avoiding Attacks on Mobile Ad-Hoc Networks*, 2007.

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