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Causal Inference Theory and Applications in Enterprise Computing

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- Lecture Organization
- Embedding: Causal Inference in a Nutshell
- Introduction to Causal Graphical Models



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Lecture Organization

Lecture Organization Topics to be Discussed



- Questions concerning Jupyter lab or R exercises?
- Open Questions concerning last week's lecture topics?

Dies Academicus (6th of May, postponed)

Exercise is happening as intended

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Embedding: Causal Inference in a Nutshell

Embedding: Causal Inference in a Nutshell Concept





E.g., what is the sailors' probability of recovery when **we see** a treatment with lemons?

Q(P) = P(recovery | lemons)

E.g., what is the sailors' probability of recovery if **we do** treat them with lemons? Q(G) = P(recovery|do(lemons)) **Causal Inference** Theory and Applications in Enterprise Computing

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Introduction to Causal Graphical Models

Introduction to Causal Graphical Models Content



- 1. Preliminaries
- 2. Causal Graphical Models
- 3. (Local) Markov Condition
- 4. Factorization
- 5. Global Markov Condition
- 6. Functional Model and Markov Conditions
- 7. Faithfulness
- 8. Outlook Causal Structure Learning
- 9. Markov Equivalence Class
- 10. Summary
- 11. Excursion: Maximal Ancestral Graphs

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• A, B, A_i events

- *X*, *Y*, *Z*, *W*, *S*, *V*^{*i*} sets of random variables
- x value of random variable
- Pr probability measure
- P_X probability distribution of X
- p density
- p(X) density of P_X (always assume the existence of joint density, w.r.t. a product measure)
- p(x) density of P_X evaluated at the point x
- $X \perp Y$ independence of X and Y
- $X \perp Y \mid Z$ conditional independence of X and Y given Z
- f, g, f_i functions of a function class $\mathcal F$



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1. Preliminaries Notation

1. Preliminaries Independence of Events

- Two events *A* and *B* are called *independent*, if
 - $\Pr(A \cap B) = \Pr(A) \cdot \Pr(B)$,

or - rewritten in conditional probabilities - if

$$Pr(A) = \frac{A \cap B}{B} = Pr(A|B),$$
$$Pr(B) = \frac{A \cap B}{A} = Pr(B|A).$$

• $A_1, ..., A_N$ are called *(mutually) independent* if for every subset $S \subset \{1, ..., N\}$ we have

$$\Pr\left(\bigcap_{i\in S}A_i\right) = \prod_{i\in S}\Pr(A_i).$$

Note:

for $N \ge 3$, pairwise independence $\Pr(A_i \cap A_j) = \Pr(A_i) \cdot \Pr(A_j)$ for all i, j where i, j = 1, ..., N, and $i \ne j$ does not imply (mutual) independence.

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1. Preliminaries Independence of Random Variables

• Two real-valued random variables X and Y are called *independent*,

if for every $x, y \in \mathbb{R}$, the events $\{X \le x\}$ and $\{Y \le y\}$ are independent,

Or, in terms of densities: for all x, y,

p(x,y) = p(x)p(y).

Note:

If $X \perp Y$, then E[X Y] = E[X] E[Y], and cov(X, Y) = E[X Y] - E[X] E[Y] = 0, i.e., $X \perp Y \Rightarrow cov(X, Y) = 0$. But: $cov(X, Y) = 0 \Rightarrow X \perp Y$.

No correlation does not imply independence

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However, we have, for large \mathcal{F} : $(\forall f, g \in \mathcal{F}: cov(f(X), g(Y)) = 0)$, then $X \perp Y$.



1. Preliminaries Conditional Independence of Random Variables

• Two real-valued random variables X and Y are called *conditionally independent* given Z,

 $X \perp\!\!\!\perp Y \mid Z$ or $(X \perp\!\!\!\perp Y \mid Z)_P$

if

$$p(x, y|z) = p(x|z) p(y|z)$$

for all x, y and for all z s.t. p(z) > 0.

Note:

It is possible to find X, Y which are conditionally independent given a variable Z but unconditionally dependent, and vice versa.

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This forms the Causal Graphical Model

2. Causal Graphical Models Definition (Pearl)

- Directed Acyclic Graph (DAG) G = (V, E)
 - Vertices V_i , i = 1, ..., N
 - □ Directed edges $E = (V_i, V_j)$, i.e., $V_i \rightarrow V_j$
 - □ No cycles
- Use kinship terminology, e.g., for path $V_i \rightarrow V_j \rightarrow V_k$
 - $\Box V_i = Pa(V_j) \text{ parent of } V_j$
 - $\Box \{V_i, V_j\} = Ang(V_k) \text{ ancestors of } V_k$
 - $\Box \{V_j, V_k\} = Des(V_i) \text{ descendants of } V_i$
- Directed Edges encode *direct causes* via
 - \Box $V_i = f_i(Pa(V_i), N_i)$ with independent noise N_i



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2. Causal Graphical Models Connecting *G* and *P*

- Basic Assumption: *Causal Sufficiency*
 - $\hfill\square$ All relevant variables are included in the DAG G



- Key Postulate: (Local) Markov Condition
- Essential mathematical concept: *d-Separation*

(describes the conditional independences required by a causal DAG)

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3. (Local) Markov Condition Theorem



(Local) Markov Condition: V_j independent of nondescendants $ND(V_j)$, given parents $Pa(V_j)$, i.e., $V_j \perp V_{V/(Des(V_j) \cup Pa(V_j))} | Pa(V_j).$

- I.e., every information exchange with its nondescendants involves its parents
- Example:



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3. (Local) Markov Condition Supplement (Lauritzen 1996)

- Assume V_N has no descendants, then $ND(V_N) = \{V_1, \dots, V_{N-1}\}$.
- Thus the local Markov condition implies

 $V_N \perp \{V_1, \dots, V_{N-1}\}/Pa(V_N) \mid Pa(V_N).$

Hence, the general decomposition

$$p(v_1, \dots, v_N) = p(v_N | v_1, \dots, v_{N-1}) p(v_1, \dots, v_{N-1})$$

becomes

$$p(v_1, ..., v_N) = p(v_N | Pa(v_N)) p(\{v_1, ..., v_{N-1}\} / Pa(v_N)).$$

Induction over N yields to

$$p(v_1, ..., v_N) = \prod_{i=1}^N p(v_i | Pa(v_i)).$$

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• I.e., the graph shows us how to factor the joint distribution P_V .



4. Factorization Definition



Factorization:

$$p(v_1, ..., v_N) = \prod_{i=1}^N p(v_i | Pa(v_i)).$$

- I.e., conditionals as causal mechanisms generating statistical dependence
- Example:



$p(v) = p(v_1, ..., v_6) = p(v_1) \cdot p(v_2) \\ \cdot p(v_3 | v_2) \cdot p(v_4 | v_1, v_2, v_3) \\ \cdot p(v_5 | v_4) \cdot p(v_6 | v_4) = \prod_{i=1}^{6} p(v_i | Pa(v_i))$

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5. Global Markov Condition D-Separation (Pearl 1988)

- *Path* = sequence of pairwise distinct vertices where consecutive ones are adjacent
- A path q is said to be *blocked* by a set S if
 - □ *q* contains a *chain* $V_i \rightarrow V_j \rightarrow V_k$ or a *fork* $V_i \leftarrow V_j \rightarrow V_k$ such that the middle node is in *S*, or
 - □ *q* contains a *collider* $V_i \rightarrow V_j \leftarrow V_k$ such that the middle node is not in *S* and such that no descendant of V_i is in *S*.

D-Separation: *S* is said to **d-separate** *X* **and** *Y* in the DAG *G*, i.e., $(X \perp Y \mid S)_G$, if *S* blocks every path from a vertex in *X* to a vertex in *Y*. **Causal Inference** Theory and Applications in Enterprise Computing



5. Global Markov Condition Blocking of Paths (I/II)

Example: Blocking of paths



- □ Path from V to Y is blocked by conditioning on W, X, or $\{W, X\}$.
- Example: Unblocking of paths



- □ Path from *V* to *Y* is blocked by \emptyset .
- □ Path from V to Y is unblocked by conditioning on W, Y, or $\{W, Y\}$.

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5. Global Markov Condition Blocking of Paths (II/II)

Example (Berkson's Paradox 1946): Unblocking by conditioning on common effects



- The path from X to Y is unblocked by conditioning on Z, i.e.,
 X ⊥ Y
 - but: X 💺 Y | Z
- E.g., the false observation of a negative correlation between two unrelated or even positive correlated traits.

Asymmetry under Inverting Arrows (Reichenbach 1956):



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5. Global Markov Condition D-Separation

- Example (Cooling House Scenario):
 - The path from V_1 to V_6 is blocked by V_4 .
 - V_1 and V_6 are d-separated by V_4 .
 - The path $V_2 \rightarrow V_3 \rightarrow V_4 \rightarrow V_6$ is blocked by V_3, V_4 , or $\{V_3, V_4\}$.
 - But: V_2 and V_6 are d-separated only by V_4 , or $\{V_3, V_4\}$.
 - The paths $V_1 \rightarrow V_4 \leftarrow V_2$ is blocked by Ø
 - ...but unblocked by conditioning on V_4 or $\{V_3, V_4\}$.
 - Note: V_1 and V_2 are d-separated by \emptyset or V_3 .
 - V_4 is a fork in $V_5 \leftarrow V_4 \rightarrow V_6$.
 - V_5 and V_6 are d-separated by V_4 .

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5. Global Markov Condition Theorem



Global Markov Condition: For all disjoint subsets of vertices X, Y and Z we have that X, Y d-separated by $Z \Rightarrow (X \perp Y \mid Z)_P$.

• I.e., we have $(X \perp Y \mid Z)_G \Rightarrow (X \perp Y \mid Z)_P$



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6. Functional Model and Markov Conditions Theorem (Lauritzen 1996, Pearl 2000)

Theorem:

The following are equivalent:

- Existence of a *functional causal model G*;
- (Local) Markov condition: statistical independence of nondescendants given parents (i.e.: every information exchange with its nondescendants involves its parents)
- Global Markov condition: d-separation (characterizes the set of independences implied by local Markov condition)
- Factorization: $p(v_1, \dots, v_N) = \prod_{i=1}^N p(v_i | Pa(v_i)).$

(subject to technical conditions)

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7. Causal Faithfulness The Key-Postulate



Causal Faithfulness:

p is called faithful relative to *G* if only those independencies hold true that are implied by the Markov condition, i.e., $(X \perp Y \mid Z)_{C} \leftarrow (X \perp Y \mid Z)_{P}$

- I.e., we assume that any population *P* produced by this causal graph *G* has the independence relations obtained by applying d-separation to it
- Seems like a hefty assumption, but it really isn't: It assumes that whatever independencies occur in it arise not from incredible coincidence but rather from structure, i.e., data generating model G.
- Hence:



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8. Outlook Causal Structure Learning Concept (Spirtes, Glymor, Scheines and Pearl)

Assumptions:

- Causal Sufficiency
- Global Markov Condition
- Causal Faithfulness

Causal Structure Learning:

 \Box Accept only those DAG's *G* as causal hypothesis for which

 $(X \perp Y \mid Z)_G \Leftrightarrow (X \perp Y \mid Z)_P.$

- Defines the basis of constraint-based causal structure learning
- Identifies causal DAG up to Markov equivalence class (DAGs that imply the same conditional independencies)

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9. Markov Equivalence Class Theorem (Verma and Pearl)

Theorem:

Two DAGs are Markov equivalent if and only if they have the same skeleton and the same *v*-structures

Skeleton:

corresponding undirected graph

V-Structure:

substructure $X \rightarrow Y \leftarrow Z$ with no edges between X and Z.



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9. Markov Equivalence Class Examples

■ Same skeleton, no *v*-structure

• Same skeleton, same *v*-structure at *W*



 $X \perp Z \mid Y$



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10. Summary Causal Graphical Models



- Causal Graphical Models formalized by DAG (directed acyclic graph) G with random variables V_i , i = 1, ..., N, as vertices.
- Causal Sufficiency, Causal Faithfulness and (Local) Markov Condition imply $(X \perp Y \mid Z)_G \Leftrightarrow (X \perp Y \mid Z)_P.$
- (Local) Markov Condition states that the density p(v₁,..., v_N) then factorizes into

 $p(v_1, \dots, v_N) = \prod_{i=1}^N p(v_i | Pa(v_i)).$

• Causal conditional $p(v_i|Pa(v_i))$ represent *causal mechanisms*.

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11. Excursion: Maximal Ancestral Graphs Motivating Example

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- Suppose, we are given the following list of dependency properties among *X*, *Y*, *Z* and *W*:
 - X ⊥ Z
 Y ⊥ W
 Y ⊥ W
 X ⊥ W
 Z ⊥ W
- Which DAG could have generated these, and only these, pattern of dependencies?
- The skeleton representing the pattern of dependencies must be:



• And there must be the following colliders:



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• There is no orientation of Y - Z that is consistent with the independencies.

11. Excursion: Maximal Ancestral Graphs DAG Models and Marginalization

• Let's include an additional variable V:



- This DAG model generates a probability distribution $P_{\{V,W,X,Y,Z\}}$ in which:
 - X ⊥ Z X ⊥ Y
 - Y ⊥L W Y ±L Z
 - *X* ⊥ *W* Z ⊥ *W*
- The marginal distribution $P_{\{W,X,Y,Z\}} = P_{\{V,WX,Y,Z\}} dv$ must adhere the same dependencies.
- But: this marginal distribution cannot be faithfully generated by any DAG.

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DAG models are not closed under marginalization!

12. Excursion: Maximal Ancestral Graphs Ancestral Graphs (informally)

Ancestral Graph (AG)

is a graph containing both directed and bi-directed edges, where the bi-directed edges stand for *latent variables, e.g.,*

m-Separation

If *S* m-separates X and Y in an ancestral graph *M*, then $X \perp Y \mid S$ in every density *p* that factorizes according to any DAG *G* that is represented by the AG *M*.

Example



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11. Excursion: Maximal Ancestral Graphs DAGs vs. AGs



Advantages of AGs

- □ AGs can faithfully represent more probability distributions than DAGs.
- □ AG models are closed under marginalization.
- AGs can (implicitly) represent unobserved variables, which exist in many (possibly almost all) applications.

Disadvantages of AGs

- Parameterization is difficult in the general case.
- Markov equivalence is difficult.

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References



Literature

- Pearl, J. (2009). <u>Causal inference in statistics: An overview</u>. Statistics Surveys, 3:96-146.
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- Spirtes, P., Glymour, C., and Scheines, R. (2000). Causation, Prediction, and Search. The MIT Press.

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Thank you for your attention!