

Emergency Detection and Response System for Vacuum Robots

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Inspired by: Connected Healthcare prof. Dr. Bert Arnrich

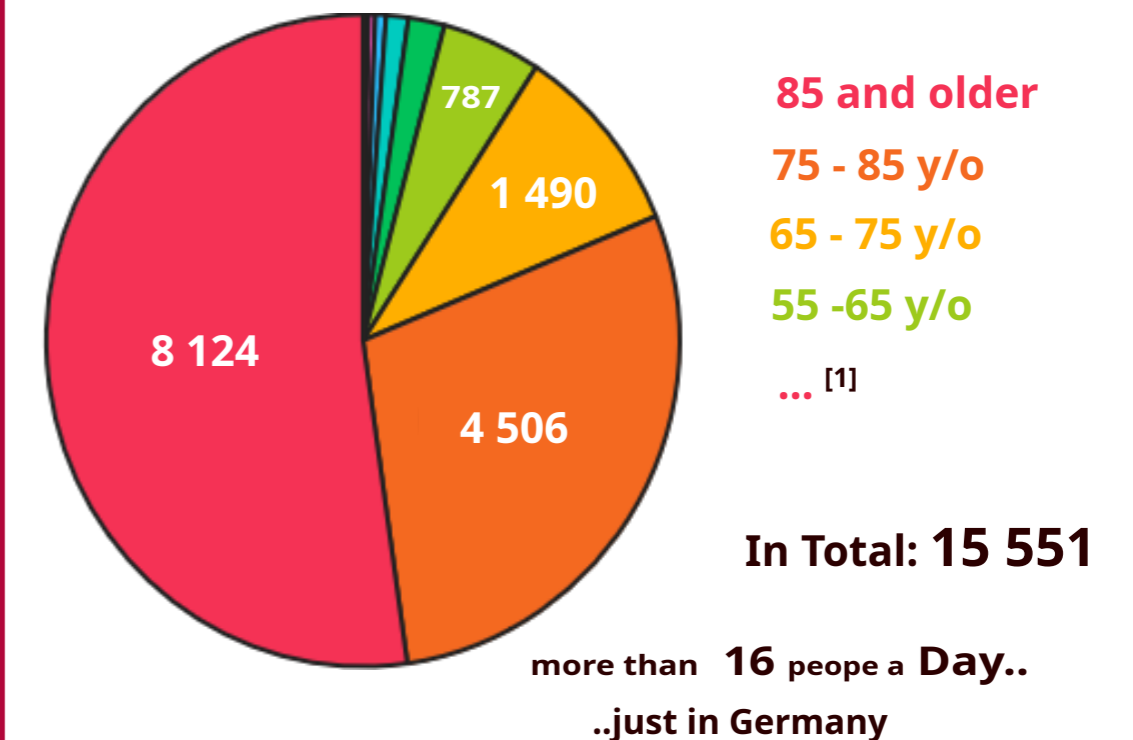
The Problem

Falls are a common cause of injury, especially for older people, or people with certain medical conditions.

Many people who fall are unable to reach a telephone or ask someone for help.

Numbers

Household Accident Fatalities by Age Group in 2022



The Idea

The goal of this project is to extend the functionality of robot vacuum cleaners by

- » open source add-on to
- » recognize when a person has fallen and/or
- » needs emergency assistance so
- » an emergency call can be sent automatically or
- » a trusted person can receive live video footage

Capabilities



Built-in Sensors:

3D camera

"to share real time video by streaming to your mobile phone" [2]

LiDAR sensors

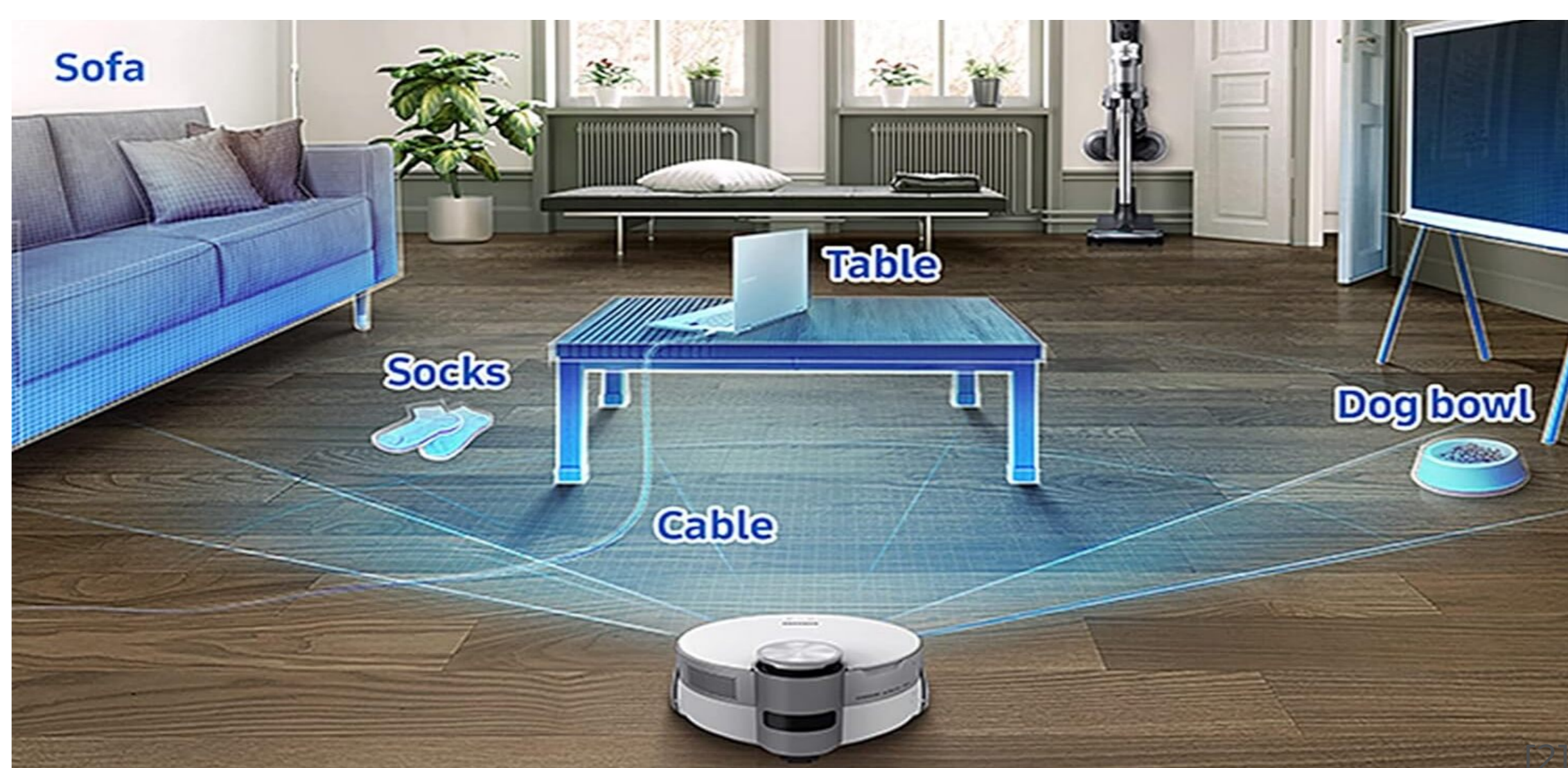
"create accurate room maps for the Jet Bot to navigate so no worrying about your robotic vacuum going to places it shouldn't"[2]

Approach

The research question is to use the existing sensors of a robot vacuum cleaner and develop a model using machine learning that recognizes human outlines in all possible positions in order to automatically make an emergency call if necessary.

- » Sensor Analysis and Enhancement
- » Integration and Testing

- » Data Collection and Model Development
- » Open-Source Cross-platform Compatibility



Abstract

This paper focuses on using the existing sensors of vacuum robots and using machine learning to develop a model that recognizes human outlines in different poses. Elderly people, but also people with certain medical conditions, especially if they live alone, are often unable to get up independently after a fall. This paper describes the development of an open source, manufacturer-independent additional function for vacuum robots that can automatically make an emergency call in the event of an emergency situation.